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Mathematical Modelling of Convective Diffusive Mass Transfer in Ferrofluids Concerning Targeted Drug Delivery

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Abstract: Magnetically targeted drug delivery systems have been gaining importance over recent years due to their efficiency and minimal side effects. Many techniques are proposed for delivering drugs to targeted sites within the human body. But magnetically targeted drug delivery surpasses because of its unique character and high efficiency. There are only a few theoretical analyses done by researchers addressing the hydrodynamic models of magnetic fluids in the blood vessel. This paper presents a mathematical model of the hydrodynamics of the fluid, blood flow, and convective diffusive mass transfer of the species. Here we have tried to analyze a drug delivery method for delivering a drug to a specific site in the body. For this analysis, we have considered a channel bounded by the tissue region where the drug is targeted. An exact analysis of unsteady convective diffusive solute transfer in a channel bounded by a tissue region under the influence of a magnetic field.

Keywords: magnetic targeting drug delivery; ferrofluids; hydrodynamic modeling; dispersion model.

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1. Introduction

Magnetically targeted drug delivery is a method for delivering a drug to a specific site in the body by attaching the drug to small paramagnetic particles (nanoparticles). This compound is injected into the bloodstream, which supplies to the targeted site under an external magnetic field. Magnetic drug targeting therapy can be used for the medical treatment of various diseases like stenosis, thrombosis, and cancer. Handan [1] has considered a blood vessel in the target region where magnetic microspheres are convicted and developed a mathematical model describing the process for a single magnetic particle. The computational fluid dynamics approach is adopted by modeling ferrofluids flow in a blood vessel. Ferrofluids are colloidal solutions of ferromagnetic nanoparticles in a carrier fluid. They need to be biodegradable to find use in medicine, and certain *in vivo* and *in vitro* experiments have been performed [2-6]. The dispersion behavior in oscillatory flows in uniform conduits is studied using a similar methodology.

Additionally, it is demonstrated that turbulent motion causes heat and other diffusible qualities to diffuse through the fluid's interior [7-9]. Many models have been developed to study nanofluid transportation in bio tissue in the case of magnetic hyperthermia by Tang, Yundong et al. [10]. Magnetic targeting of the drug under the effect of the applied magnetic field is studied numerically by Sharifi Abbas et al. [11]. Innovative models have been developed to study the electro-osmotic flow of Couette nanofluids [12]. A study on the effect of stenosis on magneto nanoparticle distributions in the presence of a magnetic field is presented by Varmazyar et al. [13]. Characteristics of various parameters of ferrofluids are studied using numerical and analytical methods by Nadeem et al. [14]. Punith Kumar et al. [15] studied the effects of convective mass transfer and magnetic field in the case of catheter-based drug delivery. Ismaeel et al. [16] reviewed and presented the methods related to nanofluid principles focusing on biofluid mass transfer. Ghulam Rasool et al. [17] studied a 2D model of treatment for cancer. The coupled governing equations are defined and solved for nanoparticle flow. Farshad Moradi Kashkooli et al. [18] examined the Darcy-Forchheimer relation numerically by considering convective nanofluid flow past a stretching sheet. A uniform magnetic field is applied over the flow, and a small Reynolds number is applied. The numerical solution is obtained for governing problems.

The drug delivery process to tumors in solid form using nano-sized drug delivery systems. Conventional therapy through various stages is compared and simulated. Punith Kumar and Indira [20] reported on various models for drug delivery systems for cancer. They discussed numerical methods and simulation models available for bio-interaction representations in biosystems. Zakaria Korei *et al.* [21] conducted research on lid-driven cavity problems considering MHD flow. Xue-Lin Gao *et al.* [22] studied impacts on heat transfer between solid and liquid. They developed a square cavity model and studied the physical properties. The Boltzmann method is used to solve the defined equations. Sukumar Pati *et al.* [23] critically reviewed forced convective heat transfer through porous media. They provided recommendations on critical areas [24-29] and discussed comparing nanofluids with traditional coolants. This is demonstrated by considering alumina water flow through parallel fins inside a hexagonal boundary.

As earlier work viewpoint cited, the general purpose is the analysis of the behavior of the flow field components; it appears in many studies that deal with the fluid flows through channels. These problems are solved using the Navier-Stokes equations. Still, the difference from one problem to another is related to the constraints associated with the flow and the type of solution sought. Regarding the constraints, it is important to point out that the Navier-Stokes equations are very sensitive to the boundary and initial conditions. This is to say, for example, that the same differential equation can formulate many problems. Still, the difference at the level of the solutions is mainly related to the boundary conditions.

On the other hand, the type of solution sought is related to the method used to solve the problem. This allows us to highlight the particularity of our current study compared to all the previous works cited at this stage. The present model, which includes hydrodynamics of the fluid, blood flow, and convective diffusive mass transfer of the species, is considered, and an analytical solution is obtained. So, this kind of solution has never been reported elsewhere.

2. Materials and Methods

A channel bounded by the tissue region where the drug is targeted considered with an external magnetic field application. Blood acts as a magnetically conducting fluid. A model similar to dusty viscous fluid is used to account for the suspensions that carry the drug.

Assuming fully developed flow (Figure 1), Navier-stokes equations in regions 1 and 2 reduce to

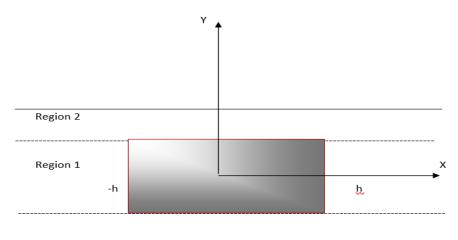


Figure 1. Schematic of physical configuration.

Region 1

$$\rho \frac{\partial u_1}{\partial t} = -\frac{\partial P}{\partial x} + \mu_1 \frac{\partial^2 u_1}{\partial v^2} + KN(v_1 - u_1) - \sigma_e B_0^2 u_1$$
(2.1)

$$m\frac{\partial v_1}{\partial t} = K\left(u_1 - v_1\right) \tag{2.2}$$

Region 2

$$\rho \frac{\partial u_2}{\partial t} = -\frac{\partial P}{\partial x} + \mu_2 \frac{\partial^2 u_2}{\partial y^2} + KN(v_2 - u_2) - \sigma_e B_0^2 u_2 - \frac{\mu_2}{K_0} u_2$$
(2.3)

$$m\frac{\partial v_2}{\partial t} = K(u_2 - v_2) \tag{2.4}$$

The boundary conditions are given by

$$\frac{\partial u_1}{\partial t} = 0$$
 at $y = 0$ (Symmetry)

$$u_1 = u_2, \quad \mu_1 \frac{\partial u_1}{\partial y} = \mu_2 \frac{\partial u_2}{\partial y} \quad at \quad y = h$$
 (Matching)

$$u_2 = 0 at y = h_1 (no-slip)$$

Nondimensionalising using $y^* = \frac{y}{h}$, $u^* = \frac{u_i}{u_0}$, $v^* = \frac{v_i}{v_0}$, and substituting

$$u_i = U_i(y)e^{-nt}$$
, $v_i = V_i(y)e^{-nt}$, $\frac{\partial P}{\partial x} = -Pe^{-nt}$ we get the equations as

$$\frac{d^2 u_1}{dv^2} + w_1^2 u_1 = -RP \quad \text{in region 1} \quad \text{and}$$
 (2.8)

$$\frac{d^2 u_2}{dy^2} + w_2^2 u_2 = -R\lambda P \text{ in region 2}$$
 (2.9)

where
$$w_1^2 = \left(\frac{KN_1}{\rho} \frac{n\tau}{1 - n\tau} + n\right) \frac{\rho h^2}{\mu_1} - \frac{\sigma_e B_1^2 h^2}{\mu_1}, \quad R = \frac{\rho h^2}{\mu_0 \mu_1}, \quad V_1 = \frac{\mu_1}{1 - n\tau}, \quad V_2 = \frac{\mu_2}{1 - n\tau}, \quad (2.10)$$

Boundary conditions after non-dimensionalizing are given by

$$\frac{\partial u_1}{\partial y} = 0 \qquad at \qquad y = 0 \tag{2.11}$$

$$u_1 = u_2, \quad \frac{\partial u_1}{\partial y} = \lambda \frac{\partial u_2}{\partial y} \quad at \quad y = 1$$
 (2.12)

$$u_2 = 0$$
 at $y = 1 + h'$

Solving (2.8) and (2.9) using (2.10) to (2.12), we get the axial velocity of the convecting fluid i.e 2blood as

$$u_1 = RP\left(a_1 \cos \omega_1 y - \frac{1}{\omega_1^2}\right) \tag{2.13}$$

$$u_2 = RP \left(a_2 \cos \omega_2 y + a_1 \sin \omega_2 y - \frac{\lambda}{\omega_2^2} \right)$$
 (2.14)

Where a_1 , a_2 and a_3 are listed in the appendix.

The average velocity over region 1 is given by

$$\overline{u}_{1} = \int_{0}^{1} u_{1} dy = RP \left(a_{3} \frac{\sin \omega_{1}}{\omega_{1}} - \frac{1}{\omega_{1}^{2}} \right)$$
 (2.15)

$$\overline{u}_{2} = \int_{0}^{1+h'} u_{2} dy = RP \left(\frac{a_{2}}{\omega_{2}} \left\{ \sin \omega_{2} (1+h') - \sin \omega_{2} \right\} - \frac{a_{1}}{\omega_{2}} \left\{ \cos \omega_{2} (1+h') - \cos \omega_{2} \right\} - \frac{\lambda h'}{\omega_{2}^{2}} \right)$$
(2.16)

The particle velocity $V_i(y)$ for i=1,2 can be obtained from (2) and (4) using the assumption

$$V_i = \frac{u_i(y)}{1 - n\tau}$$
, for $i = 1, 2$ (2.16a)

In a drug delivery system, it is necessary to keep track of the concentration of each species. The convective diffusive species equation in both regions is given by

Region 1

$$\frac{\partial C_1}{\partial t} + u_1 \frac{\partial C_1}{\partial x} + \frac{KN}{\rho} \left(\frac{\partial C_1}{\partial t} + v_1 \frac{\partial C_1}{\partial x} \right) = D_1 \left(\frac{\partial^2 C_1}{\partial x^2} + \frac{\partial^2 C_1}{\partial y^2} \right)$$
(2.17)

Region 2

$$\frac{\partial C_2}{\partial t} + u_2 \frac{\partial C_2}{\partial x} + \frac{KN}{\rho} \left(\frac{\partial C_2}{\partial t} + v_2 \frac{\partial C_2}{\partial x} \right) = D_2 \left(\frac{\partial^2 C_2}{\partial x^2} + \frac{\partial^2 C_2}{\partial y^2} \right)$$
(2.18)

The drug, in the form of a suspension, is mixed with a biocompatible ferrofluid and injected into the blood flow. Due to this, the initial and boundary conditions are given by:

$$C_1(0,x,y) = C_0$$
 and $C_2(0,x,y) = 0$ (initial conditions) (2.19)

$$\frac{\partial C_1}{\partial y} = 0$$
 at $y = 0$ (symmetry)

$$C_1 = C_2, \quad D_1 \frac{\partial C_1}{\partial y} = D_2 \frac{\partial C_2}{\partial y} \quad at \quad y = h$$
 (matching) (2.21)

$$\frac{\partial C_2}{\partial y} = 0$$
 at $y = h_1$ (no flux condition) (2.22)

$$C_1(t, \infty, y) = C_2(t, \infty, y) = 0$$
 (2.23)

The above equations are non-dimensionalized using the parameters and neglecting *

$$y^* = \frac{y}{h}$$
, $u^* = \frac{u_i}{u_0}$, $v^* = \frac{v_i}{v_0}$, $\tau^* = \frac{D_1 t}{h^2}$, $\theta_i = \frac{C_i}{C_0}$, $X = \frac{D_1 x}{h^2 u_0}$ we get

Region 1

$$\frac{\partial \theta_1}{\partial \tau} + \phi_1 u_1 \frac{\partial \theta_1}{\partial X} = \chi_i \left(\frac{1}{Pe^2} \frac{\partial^2 \theta_1}{\partial X^2} + \frac{\partial^2 \theta_1}{\partial Y^2} \right)$$
 (2.24)

Region 2

$$\frac{\partial \theta_2}{\partial \tau} + \phi_2 u_2 \frac{\partial \theta_2}{\partial X} = \chi_i \left(\frac{1}{Pe^2} \frac{\partial^2 \theta_2}{\partial X^2} + \frac{\partial^2 \theta_2}{\partial Y^2} \right)$$
 (2.25)

Where

$$\phi_{1} = \frac{1 + \frac{\Gamma_{1}}{1 - n\tau}}{1 + \Gamma_{1}}, \Gamma_{1} = \frac{KN_{1}}{\rho}, Pe^{2} = \frac{u_{0}^{2}h^{2}}{D_{1}^{2}}, \phi_{2} = \frac{1 + \frac{\Gamma_{2}}{1 - n\tau}}{1 + \Gamma_{2}}, \Gamma_{2} = \frac{KN_{2}}{\rho}, \chi_{1} = \frac{1}{1 + \Gamma_{1}}, \chi_{2} = \frac{D_{2}}{D_{1}} \frac{1}{1 + \Gamma_{2}}$$

Initial and boundary conditions become

$$\theta_1(0, x, y) = 1$$
 and $\theta_2(0, x, y) = 0$ (initial conditions) (2.26)

$$\theta_1 = \theta_2, \quad \frac{\partial \theta_1}{\partial y} = \Lambda_1 \frac{\partial \theta_2}{\partial y} \quad at \quad y = 1, \ \Lambda_1 = \frac{D_2}{D_1}$$
 (matching) (2.27)

$$\frac{\partial \theta_2}{\partial y} = 0$$
 at $y = 1 + h'$, (no flux condition) (2.28)

$$\theta_1(t, \infty, y) = \theta_2(t, \infty, y) = 0 \tag{2.29}$$

2.1. Dispersion model.

Let us use the generalized dispersion model proposed by Gill and Sankarasubramanian [24] and solve (2.24), (2.25) using the boundary conditions (2.26) to (2.29), obtaining

$$\theta_{i} \Sigma_{K=0}^{\infty} f_{iK} \left(\tau, y \right) \frac{\partial^{K} \theta_{m}}{\partial X^{K}}, i = 1, 2$$
(2.30)

Where
$$\theta_{mi} = \int_{h_{i-1}}^{h_i} \theta_i dY$$
 is the mean concentration (2.31)

Integrating (24) and (25) w.r.t Y between h_i and h_{i-1} , we get

$$\frac{\partial \theta_{mi}}{\partial \tau_{i}} + \phi_{1} \frac{\partial}{\partial X} \int_{h_{i}}^{h_{i}} u_{i} \theta_{i} dY = \chi_{i} \left(\frac{1}{Pe^{2}} \frac{\partial^{2} \theta_{mi}}{\partial X^{2}} + \left| \frac{\partial \theta_{i}}{\partial Y} \right|_{h_{i}}^{h_{i}} \right), i = 1, 2$$
(2.32)

Assuming θ to be diffusive in nature, let us introduce the dispersion coefficient into the model as

$$\frac{\partial \theta_{mi}}{\partial \tau_i} = \sum_{j=0}^{\infty} K_{ij} \frac{\partial^j \theta_{mi}}{\partial X^j}, \quad j = 1, 2$$
(2.33)

We can find the values of K_{ij} by equating the coefficients of $\frac{\partial^j \theta_{mi}}{\partial X^j}$, j = 0, 1, 2, ... as

$$K_{ij}(\tau) = \chi_i \frac{\delta j^2}{Pe^2} + \chi_i \left| \frac{\partial \theta_i}{\partial Y} \right|_{h_{i-1}}^{h_i} - \phi \int_{h_{i-1}}^{h_i} u_i f_{ij-1} dY$$
(2.34)

where $f_{ij-1} = 0$ and δ_{ij} is the Kronecker delta defined as $\delta_{ij} = \begin{cases} 1, & \text{for } i = j \\ 0, & \text{for } i \neq j \end{cases}$

Equation (2.33) can be truncated after the terms K_{12} and K_{22} without causing errors because the higher terms are negligibly small. The resulting model for the mean concentration will be of the form

For region 1

$$\frac{\partial \theta_{m_1}}{\partial \tau_1} = K_{10}(\tau_1)\theta_{m_1} + K_{11}(\tau_1)\frac{\partial \theta_{m_1}}{\partial X} + K_{12}(\tau_1)\frac{\partial^2 \theta_{m_1}}{\partial X^2}$$
(2.35)

For region 2

$$\frac{\partial \theta_{m_2}}{\partial \tau_2} = K_{20}(\tau_2)\theta_{m_2} + K_{21}(\tau_2)\frac{\partial \theta_{m_2}}{\partial X} + K_{22}(\tau_2)\frac{\partial^2 \theta_{m_2}}{\partial X^2}$$
(2.36)

To solve (2.35) and (2.36), we need the values of K_{ij} for i, j = 0,1,2, along with the boundary conditions. To find these values, we require the corresponding values of f_{ik} for i = 1,2. Hence we substitute (2.30) into (2.34) and (2.35) and use (2.32) to get

$$\frac{\partial f_{ik}}{\partial \tau_i} = \chi_i \frac{f_{i,k-2}}{Pe^2} + \chi_i \left(\frac{\partial^2 f_{ik}}{\partial Y^2} \right) - \phi_i u_i f_{ik-1} - \Sigma_{j=0}^l K_{i,k-j}, i = 1, 2, k = 0, 1, 2, \dots$$
 (2.37)

The initial and boundary conditions required to solve (37) are

$$\theta_{mi} = \int_{h_{i-1}}^{h_i} \theta_i(0, X, Y) dY, f_{i,k}(0, Y) = 0 \text{ for } i = 1, 2$$
(2.38)

$$\frac{\partial f_{10}}{\partial Y} = 0 \qquad at \qquad Y = 0 \tag{2.39}$$

$$f_{10} = f_{20}, \quad \frac{\partial f_{10}}{\partial Y} = \Lambda \frac{\partial f_{20}}{\partial Y} \quad at \quad Y = 1,$$
 (2.40)

$$\frac{\partial f_{20}}{\partial Y} = 0 \qquad at \qquad Y = 1 + h', \tag{2.41}$$

$$\theta_{mi}(\tau,\infty) = \frac{\partial \theta_{mi}}{\partial X}(\tau,\infty) = 0 \quad \text{for} \quad i = 1,2$$
 (2.42)

The values of K_{i0} can be obtained from (2.34) as

$$K_{i0} = \chi_i \left| \frac{\partial f_{i0}}{\partial Y} \right|_{h_{i,1}}^{h} \quad \text{for } i = 1, 2$$
 (2.43)

The values of f_{i0} can be obtained from (2.37) as

$$\frac{\partial f_{i0}}{\partial \tau_i} = \chi_i \frac{\partial^2 f_{i0}}{\partial Y^2} - K_{i0} f_{i0} \quad \text{for} \quad i = 1, 2$$
(2.44)

The solution of (2.44) may be formulated as

$$f_{i0} = \exp\left(-\int_{0}^{\tau_{i}} K_{i0}(\eta) d\eta \ g_{i0}(\tau_{i}, Y)\right) \ for i = 1, 2$$
 (2.45)

where g_{i0} must satisfy the following:

$$\frac{\partial g_{i0}}{\partial \tau_i} = \chi_i \frac{\partial^2 g_{i0}}{\partial Y^2} \quad \text{for } i = 1, 2$$
 (2.45a)

$$f_{10}(0,Y) = g_{10}(0,Y) = \frac{g_{10}(\tau,Y)}{\int_{0}^{1} g_{10}(\tau,Y)dY}$$
(2.45b)

$$f_{20}(0,Y) = g_{20}(0,Y) = \frac{g_{20}(\tau,Y)}{\int_{-1}^{1+h'} g_{20}(\tau,Y)dY}$$
(2.45c)

$$\frac{\partial g_{10}}{\partial Y} = 0, \qquad at \qquad Y = 0 \tag{2.45d}$$

$$g_{10} = g_{20}, \quad \frac{\partial g_{10}}{\partial Y} = \Lambda \frac{\partial g_{20}}{\partial Y} \quad at \qquad Y = 1$$
 (2.45e)

$$\frac{\partial g_{20}}{\partial Y} = 0 \qquad at \qquad Y = 1 + h' \tag{2.45f}$$

The solution of (2.45a) using (2.45b) to (2.45f) is obtained as

$$g_{10}(\tau_1, Y) = \sum_{n=0}^{\infty} A_{1n} e^{-\xi_{1n}^2 \tau_1} \cos \mu_{1n} Y$$
 (2.46a)

$$g_{20}(\tau_2, Y) = \sum_{n=0}^{\infty} A_{2n} e^{-\xi_{2n}^2 \tau_2} (\cos \mu_{2n} Y + \tan \mu_{1n} (1 + h') \sin \mu_{2n} Y)$$
 (2.46b)

Where
$$\mu_{1n}$$
, μ_{2n} are the roots of $-\mu_{1n} \tan \mu_{1n} = \Lambda \mu_{2n} \tan \mu_{2n} h'$, for $n = 0, 1, 2, ...$ (2.46c)

The expansion coefficients A_{1n} , A_{2n} are given by

$$A_{1n} = \frac{4\sin\mu_{1n}}{2\mu_{1n}^2 + \mu_{1n}\sin 2\mu_{1n}},$$

(2.46d)

$$A_{2n} = 4s \left(\frac{4\sin \mu_{2n} (1+h') - \sin \mu_{2n}}{h' + \sin 2\mu_{1n} (1+h') - \sin 2\mu_{2n} - \tan \mu_{2n} (1+h') \cos 2\mu_{2n} (1+h') + \tan \mu_{2n} \cos 2\mu_{2n}}, \right)$$
(2.46e)

Using (45) in (44) we get the following values of f_{ij} and K_{ij} as

$$f_{10}(\tau_1, Y) = \frac{\sum_{n=0}^{\infty} A_{1n} e^{-\xi_{1n}^2 \tau_1} \cos \mu_{1n} Y}{\sum_{n=0}^{\infty} \frac{A_{1n}}{\mu_{1n}} e^{-\xi_{1n}^2 \tau_1} \sin \mu_{1n} Y},$$
(2.47a)

$$f_{20}(\tau_2, Y) = \frac{\sum_{n=0}^{\infty} A_{2n} e^{-\xi_{2n}^2 \tau_2} \left(\cos \mu_{2n} Y + \tan \mu_{2n} (1 + h') \sin \mu_{2n} Y\right)}{\sum_{n=0}^{\infty} \frac{A_{2n}}{\mu_{2n}} e^{-\xi_{2n}^2 \tau_2} \left(\sin \mu_{2n} (1 + h') - \sin \mu_{2n} + \tan \mu_{2n} (1 + h') \left(\cos \mu_{2n} - \cos \mu_{2n} (1 + h')\right)\right)}, \quad (2.47b)$$

$$K_{10}(\tau_1) = -\chi_1 \frac{\sum_{n=0}^{\infty} A_{1n} \mu_{1n} e^{-\xi_{1n}^2 \tau_1} \sin \mu_{1n} Y}{\sum_{n=0}^{\infty} \frac{A_{1n}}{\mu_{1n}} e^{-\xi_{1n}^2 \tau_1} \sin \mu_{1n} Y},$$
(2.47c)

As
$$\tau_1 \to \infty$$
, we get $K_{10}(\infty) = -\chi_1 \mu_{10}^2$ (2.47d)

$$K_{20}(\tau_2) = -\chi_2 \frac{\sum_{n=0}^{\infty} A_{2n} e^{-\xi_{2n}^2 \tau_2} \left(-\sin \mu_{2n} (1+h') + \sin \mu_{2n} + \tan \mu_{2n} (1+h') \left(-\cos \mu_{2n} + \cos \mu_{2n} (1+h')\right)\right)}{\sum_{n=0}^{\infty} \frac{A_{2n}}{\mu_{2n}} e^{-\xi_{2n}^2 \tau_2} \left(-\sin \mu_{2n} (1+h') - \sin \mu_{2n} + \tan \mu_{2n} (1+h') \left(-\cos \mu_{2n} + \cos \mu_{2n} (1+h')\right)\right)}, \quad (2.47e)$$

As
$$\tau_2 \to \infty$$
, we get $K_{20}(\infty) = -\chi_2 \mu_{20}^2$ (2.47f)

where μ_{10} and μ_{20} are the roots of (2.46c).

Now to find the asymptotic values of K_{ik} , we consider the mean velocity of the fluid flow given by (2.45) and (2.46).

Let us inject the solute into the flow for large values of the time. Then the steady-state function $f_{ik}(Y)$ satisfies the equation

For region 1

$$\frac{d^2 f_{1k}}{\partial Y^2} + \mu_{10}^2 f_{1k} = \frac{u_1}{\overline{u}_1} \frac{\phi_1 f_{1k-1}}{\chi_1} - \frac{1}{\chi_1} \sum_{j=1}^{k-1} K_{ij} f_{1k-j} + K_{1k} f_{10} \frac{1}{\chi_1}, \quad k = 1, 2, \dots$$
 (2.48)

The boundary conditions required to solve (2.48) are

$$\frac{df_{1k}}{\partial Y} = 0 \quad at \quad Y = 0 \tag{2.49}$$

Using (2.23) and (2.25) we get

$$K_{1k} = \frac{\frac{df_{1k}}{dY}\Big|_{Y=1} \cos \mu_{10} + f_{1k}\mu_{10} \sin \mu_{10} - \int_{0}^{1} \left(\frac{u_{1}}{\overline{u_{1}}} \frac{\phi_{1}f_{1k-1}}{\chi_{1}} - \frac{f_{1k-2}}{Pe^{2}} + \frac{1}{\chi_{1}} \sum_{j=1}^{k-1} K_{ij} f_{ik-j}\right) dY}{\int_{0}^{1} \frac{1}{\chi_{1}} f_{10} \cos \mu_{10} Y dY}$$
(2.50)

For region 2

$$\frac{d^2 f_{2k}}{\partial Y^2} + \mu_{20}^2 f_{2k} = \frac{u_2}{\overline{u}_2} \frac{\phi_2 f_{2k-1}}{\chi_2} - \frac{f_{2k-1}}{Pe^2} + \frac{1}{\chi_2} \sum_{j=1}^{k-1} K_{ij} f_{2k-j} + K_{2k} f_{20} \frac{1}{\chi_2}, \quad k = 1, 2, \dots$$
 (2.50a)

The boundary conditions required to solve (50a) are

$$\frac{df_{2k}}{\partial Y} = 0 \quad at \quad Y = 1 + h' \tag{2.51}$$

Using (2.23) and (2.25) we get

$$K_{2k} = \frac{-\frac{df_{2k}}{dY}\Big|_{Y=1} \cos \mu_{20} + f_{2k}\mu_{20} \sin \mu_{20} (1+h') - f_{2k} \sin \mu_{20} - \int_{0}^{1+h'} \left(\frac{u_2}{\overline{u}_2} \frac{\phi_2 f_{2k-1}}{\chi_2} - \frac{f_{2k-2}}{Pe^2} + \frac{1}{\chi_2} \sum_{j=1}^{k-1} K_{ij} f_{ik-j}\right) \cos \mu_{20} Y dY}{\int_{0}^{1+h'} \frac{1}{\chi_2} f_{20} \cos \mu_{20} Y dY}$$

$$(2.52)$$

Let the solution of (2.48) and (2.51) be formulated as

$$f_{ik} = \sum_{j=0}^{\infty} B_{j,ik} \cos \mu_{ij} Y \text{ for } i = 1,2$$
 (2.52a)

Then substituting (2.44a) into (2.48) and (2.51), we get

For region 1

$$f_{j,1k} = \frac{1}{\mu_{10}^2 - \chi_1 \mu_{1j}^2} \left(-\frac{\chi_1}{Pe^2} \sum_{j=1}^{\infty} B_{j,k-2} + \sum_{j=1}^{\infty} K_{ij} B_{j,k-j} + \left(\frac{1}{2} + \frac{\sin 2\mu_{ij}}{4\mu_{ij}} \right)^{-1} \phi_l \sum_{j=1}^{\infty} B_{j,k-j} I(j,l) \right)$$
(2.52b)

where $I_1(j,l) = \int_0^1 \frac{u_1}{\overline{u_1}} \cos \mu_{1j} Y \cos \mu_{1l} Y dY$

$$I_{1}(j,l) = \frac{RP}{\overline{u}_{1}} \begin{bmatrix} \frac{1}{\left(\omega_{1}^{2} - \left(\mu_{1j} + \mu_{1l}\right)^{2}\right)} \left(\omega_{1} \sin \omega_{1} \cos(\mu_{1j} + \mu_{1l}) - (\mu_{1j} + \mu_{1l}) \cos \omega_{1} \sin \mu_{1j}\right) + \\ \frac{1}{\left(\omega_{1}^{2} - \left(\mu_{1j} + \mu_{1l}\right)^{2}\right)} \left(\omega_{1} \sin \omega_{1} \cos(\mu_{1j} - \mu_{1l}) - (\mu_{1j} - \mu_{1l}) \cos \omega_{1} \sin \mu_{1j} - \mu_{l}\right) \end{bmatrix} + \\ \frac{1}{\left(\omega_{1}^{2} - \left(\mu_{1j} + \mu_{1l}\right)^{2}\right)} \left(\mu_{1j} \sin \mu_{1j} \cos \mu_{1j} - \mu_{1l} \cos \mu_{1l} \sin \mu_{l}\right)$$

$$(2.53a)$$

$$I_{1}(j,l) = \frac{RP}{\overline{u}_{1}} \left[a_{3} \left(\frac{\sin \omega_{1}}{2\omega_{1}} + \frac{1}{\left(2\left(\omega_{1}^{2} - 4\mu_{1j}^{2}\right)\right)} \right) \left(\omega_{1} \sin \omega_{1} \cos 2\mu_{1j} - 2\mu_{1l} \cos \omega_{1} \sin 2\mu_{1j}\right) - \frac{1}{2\omega_{1}^{2}} - \frac{1}{4\omega_{1}^{2}\mu_{1j}} \sin 2\mu_{1j} \right) \right], for(j = l)$$

$$(2.53b)$$

For region 2

$$B_{j,2k} = \frac{1}{\mu_{20}^2 - \chi_2 \mu_{2j}^2} \left(-\frac{\chi_1}{Pe^2} \sum_{j=1}^{\infty} B_{j,k-2} + \sum_{j=1}^{\infty} K_{ij} B_{j,2k-j} + \phi_2 \left(\frac{h'}{2} + \frac{1}{4\mu_{2j}} \left(\sin \mu_{2j} \left(1 + h' \right) \right) - \sin \mu_{2j} \right)^{-1} \sum_{j=1}^{\infty} B_{j,2k-1} I_2(j,l) \right)$$

(2.53c)

where
$$I_2(j,l) = \int_0^{1+h'} \frac{u_1}{\overline{u_1}} \cos \mu_{2j} Y \cos \mu_{2l} Y dY$$

$$I_{2}(j,l) = \frac{RP}{2\overline{u}_{2}} \begin{bmatrix} \frac{a_{2}}{\omega_{2}} (\sin \omega_{2}(1+h') - \sin \omega_{2}) + \frac{a_{2}}{(\omega_{2}^{2} - 4\mu_{2j}^{2})} \\ \frac{a_{2}}{(\omega_{2}^{2} - 4\mu_{2j}^{2})} (\omega_{2} \sin \omega_{2}(1+h') \cos 2\mu_{2j} (1+h') - 2\mu_{2j}) \\ \frac{a_{1}}{\omega_{2}} (\cos \omega_{2}(1+h') - \cos \omega_{2}) - \frac{a_{1}}{(\omega_{2}^{2} - 4\mu_{2j}^{2})} (\omega_{2} \cos \omega_{2} 2\mu_{2j} (h') \cos 2\mu_{2j} (1+h') - 2\mu_{2j}) \\ \frac{a_{1}}{(\omega_{2}^{2} - 4\mu_{2j}^{2})} (\omega_{2} \cos \omega_{2} \cos 2\mu_{2j} + 2\mu_{2j} \sin \omega_{2} \sin 2\mu_{2j}) - \frac{\lambda h'}{\omega_{2}^{2}} - \frac{\lambda \mu'}{2\omega_{2}^{2} 4\mu_{2j}} (\sin 2\mu_{2j} (1+h') - \sin 2\mu_{2j}) \end{bmatrix}, for(j = l)$$

(2.53d)

$$I_{2}(j,l) = \frac{RP}{\bar{u}_{2}} \frac{1}{\left(\mu_{2j}^{2} - \mu_{2l}^{2}\right)} \begin{pmatrix} \mu_{2j} \sin \mu_{2j} (1+h') \cos \mu_{2l} (1+h') - \mu_{2l} \cos \mu_{2j} (1+h') \sin \mu_{2l} (1+h') - \mu_{2l} \sin \mu_{2j} \cos \mu_{2l} + \mu_{2l} \cos \mu_{2j} \sin \mu_{2l} \end{pmatrix}, for(j \neq l) \quad (2.53e)$$

The solution for (2.45) and (2.46) using (2.48) and (2.52) are as follows:

For region 1,

$$\theta_{m_{1}} = \frac{1}{2} \left(erf \left(\frac{\phi - X_{1}}{2\sqrt{T}} \right) + erfc \left(\frac{\phi - X_{1}}{2\sqrt{T}} \right) \right) e^{\xi}$$

$$\int_{0}^{\tau} K_{10}(Z) dZ = K_{10}\tau_{1}, X_{1} = \xi_{1} + \int_{0}^{\tau_{1}} K_{11}(Z) dZ = \xi_{1} + K_{11}\tau_{1}$$

$$T = \int_{0}^{\tau_{1}} K_{12}(Z) dZ = K_{12}\tau_{1}.$$
(2.54)

where

For region 2,

$$\theta_{m_2} = \frac{1}{\sqrt{2T_0}} \exp\left(\tau_0 - \frac{X_0^2}{4T_0}\right) \tag{2.55}$$

where

$$\begin{split} \xi_0 &= \int\limits_0^{\tau_2} K_{20}(Z) dZ = K_{20} \tau_2, X_0 = \xi_2 + \int\limits_0^{\tau_2} K_{21}(Z) dZ = K_{21} \tau_2, \\ T_0 &= \int\limits_0^{\tau_2} K_{22}(Z) dZ = K_{22} \tau_2. \end{split}$$

3. Results and Discussion

An exact analysis of unsteady convective diffusive solute transfer in a channel bounded by a tissue region under the influence of a magnetic field is analyzed using the approach of Sankarasubramanian and Gill [24]. Due to the applied magnetic field, the injected drug convicted and diffused in the blood flow will be directed towards the tissue region. Degradation can occur only after initialization into tissue cells.

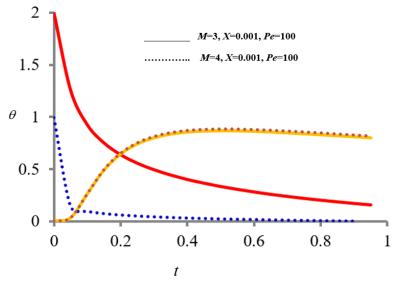


Figure 2. Concentration profile vs. time for different values of magnetic parameter M.

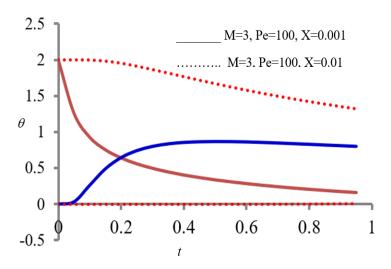


Figure 3. Concentration profile vs time for different values of axial position *X*.

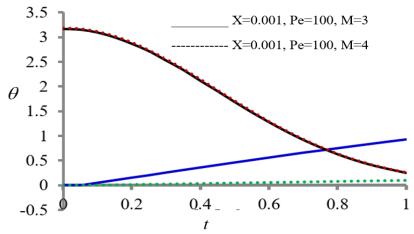


Figure 4. Concentration profile Vs Axial position for different values of magnetic parameter *M*.

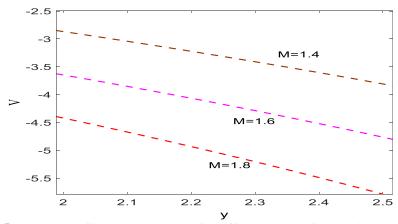


Figure 5. Velocity Profiles in lumen region for different values of magnetic parameter M.

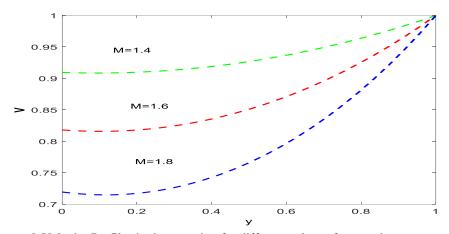


Figure 6. Velocity Profiles in tissue region for different values of magnetic parameter M.

Figures 2-4 show concentration profiles for regions 1 and 2 for different values of magnetic parameter M, Peclet number P_e and axial position X.

Concentration θ_1 in lumen decreases with time and θ_2 in the tissue region increases and reaches a constant value. The effect of magnetic field results in a decrease of θ_1 in a lesser time, indicating more solute is moving towards the tissue where there is a slight increase of θ_2 in region 2 with an increase in M. The fluid is injected at X=0. The presence of a magnetic field around this region shows dispersion at X=0.001 is at a faster rate than at X=0.01, which is a bit away from the magnetic field.

Figs. 5- 6 show velocity profiles for regions 1 and 2, respectively, for different values of magnetic parameter M. As M increases, the velocity in both regions decreases. As M increases to a higher value, the velocity becomes pulsatile, which can be seen at M=1.8, where there is a negative region for velocity. The magnetic field creates resistance to the flow of the ferrofluid and attracts the target tissue region due to a reduction in velocity.

Using an external magnetic field directs the solute diffusion towards the magnetic field where the drug is supposed to act. This analysis can be used to study targeted drug delivery and similar situations occurring in other applications.

4. Conclusions

A study on the effect of magnetic properties on drug delivery using analytical methods is presented. Suspended nanoparticles carry drugs from the lumen region to the surrounding tissue region. This is modeled by considering a dusty viscous fluid. A dispersion model proposed by Sankarasubramanian and Gill [24] is modified to account for mass transfer. Pulsatile flow is caused by the magnetic field and affects mass transfer. According to the graphs, the mass transfer will increase from the lumen region to the tissue region. Magnetic parameter and Peclet number are the parameters that significantly affect carrying drugs toward the tissue.

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Conflicts of Interest

The authors declare no conflict of interest.

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